

IDENTIFICATION

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MEDINIAD

SICK Sensor Intelligence.

NOTES ON THE WEBINAR

- The Webinar will be recorded!
- If you would like to receive the presentation and / or the recording afterwards you have to sign GDPR!



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SICK

Sensor Intelligence.

IDENTIFICATION CONTENT



I. Barcode reading 1D (laserbased)

- Basics (working principle, versions, construction of 1D barcode, Focus technology, reading diagramm..)
- Target applications

2. Barcodereading 2D (camerabased)

- Basics (operation principle, versions, construction of 2D barcode, reading diagramm..)
- Target applications

• 3. Laser vs. Camera

Laserbased barcodereader vs. camerabased barcodereader



• 4. RFID

- Basics (operation principle HF/UHF, frequenzies, technology, transponders, readingfield diagramm..)
- Target applications

5. RFID vs. Barcode

RFID Technology vs. Barcode Technology

• 6. Overview product portfolio Identification technologies

- Laser based
- Camera based
- ► RFID
- ► 4D Pro- concept

1. BARCODE READING 1D (LASER BASED) WORKING PRINCIPLE



Bar code scanners

- A laser spot is reflected by the mirror wheel onto the object (code)
- By turning the mirror wheel, the laser spot is move through the field of view
 => "Scanning the barcode"
- The remission of the laser spot is reflected into the receiver
- The receiver evaluates the intensity of the received signal
- The black and white bars of the code are read

Barcode Binary signal _____



1. BARCODE READING 1D (LASER BASED) LASERCLASS 2



• Laserclass 2

Lasbased barcodereader consists of a class 2 laser

Laser	Hazards	Eyes				Skin	Power ³⁾	Spectrum
class		Direct exposure		Diffuse reflection				λ
		w/o optical	with optical	w/o optical	with optical			
2	Safe for skin and eyes at direct exposure < 0.25 s (by closing the eyes consciously and active aversion) and diffuse reflection.	Safe at exposure time	Safe at exposure time	Safe	Safe	Safe	< 1 mW	400 nm 700 nm
	Potentially hazardous for eyes at direct exposure > 0.25 s.	<0.25 s	< 0.25 s				Class 1	other

It is recommended to use a trigger (hardware or software based)

- To open the reading field only if a product is in front of the scanner (protects the eyes)
- To save lifte time of the laser diode
- Without trigger it is not possible to recognize a "NO READ"





1. BARCODE READING 1D (LASER BASED) CONSTRUCTION OF A BARCODE



Modulwidth

- Is the narrowest dark bar in mm (min bar width)
- Only if you know the modul width you can select the right barcodescanner !
- Quit zone
 - Is the area before and after the barcode, should be 10 times bigger than the modul width (necessary to have a good reading performance)
- Start and Stop sign
 - Defined the beginning and the end of the label, each barcode have theyr own start and stop sign.



1. BARCODE READING 1D (LASER BASED) VERSIONS



- 1D Code Reader as Line Scanner, Raster Scanner or Oscillating Mirror Version
- 1D Code Reader with Standard and SMART Decoder (coderecunstruction)



1. BARCODE READING 1D (LASER BASED) BARCODE ORIENTATION

- Fence oriented
 - You have to use a Raster scanner > dynamic and stand still reading



- You have to use a Raster scanner > stand still reading
- ► You have to use a Line scanner > dynamic reading

Iranspo

- Not oriented
 - You have to use a "omnidirectional barcodereading system"

Scan pattern on the belt

Start trioger



Transpo



1. BARCODE READING 1D (LASER BASED) WHAT DOES A RED LASER SEES



Colour combination's

Suitable and unsuitable combinations



Suitable combinations	Unsuitable combinations
Black on white	Yellow on white
Blue on white	Orange on white
Black on orange	Red on white
Blue on orange	Light Brown on white
Green on white	Black on green
Dark Brown on white	Black on blue
Black on yellow	Black on dark brown
Blue on yellow	Black on blue-green
Green on yellow	Red on light brown
Green on red	Blue-Green on black

1. BARCODE READING 1D (LASER BASED) FOCUS TECHNOLOGY



- To read bar codes with specific resolution in different distances, orientations and positions, several types of focus technology are used:
 - Fix-focus technology
 - Dynamic-focus Technology
 - Auto-focus Technology







1. BARCODE READING 1D (LASER BASED) READING FIELD





Example of a reading diagramm (fix focus device)





Reading conditions:

Resolution	Scanning frequency
0.35 (13.8 mil)	750 Hz
0.50 (19.7 mil)	900 Hz
1.00 (39.5 mil)	1,200 Hz

1. BARCODE READING 1D (LASER BASED) TARGET APPLICATIONS WITH ORIENTED BARCODE

Storage and Conveyor

- ► tote reading
- box reading

Challenges:

- Short reading distance with large reading field height
- Large code length
- Low contrast codes
- Scanner close to conveyor

- CLV615 reading fields optimized on intralogistics systems
- Mounting on all standard conveyor system profiles is possible
- ► Available as kit: CLV615-F2000 with CDF600-2 PROFIBUS + PROFINET.





1. BARCODE READING 1D (LASER BASED) TARGET APPLICATIONS WITH ORIENTED BARCODES

Medical analyzer

Challenges:

- Code quality vary
- Decoding of low contrast codes
- Position of bar code varies
- Short reading distance with large reading field height
- Different specific integration requirements

- code reconstruction software SMART helps reading damaged codes
- Optimized optics for low contrast applications
- Optimized reading field in case of short distance and field height





1. BARCODE READING 1D (LASER BASED) TARGET APPLICATIONS WITH ORIENTED BARCODES



Commercial Goods

- read after print
- Packaging

Challenges:

- Shiny material / low contrast codes
- ► IP65 is required
- Advanced match codes

- Compact design enables installation even in applications with limited space
- Optimized optics for low contrast applications





1. BARCODE READING 1D (LASER BASED) TARGET APPLICATIONS WITH NON ORIENTED BARCODES



CEP (Courier express parcle)

Omnidrectional reading

Challenges:

- The labels are not oriented
- High DOF (depth of field)
- High conveyour speed
- No gap between the parcels (Tracking)

- Compact design enables installation even in applications with limited space
- Optimized optics for low contrast



2. BARCODE READING 2D (CAMERA BASED) WORKING PRINCIPLE





2. BARCODE READING 2D (CAMERA BASED) EXPLANATIONS (FOV, WD/RD, DOF)



- Field of view (FOV)
 - ► Is what the camera sees (x & y)



- Working or Reading Distance (WD/RD)
 - The Working Distance (WD) or Reading Distance (RD) is the lens-to-object distance

- Depth of Field (DOF)
 - Is the range in which a sensor can read a code, without changing focal position or lens.



2. BARCODE READING 2D (CAMERA BASED) EXPLANATIONS (FOCAL LENGTH AND LENS)



- The view angle of the lens determines how much of the visual scene the camera sees
 - Wide angle (short focal length) captures a large scene
 - Normal
 - Narrow angle, or tele (long focal length), captures a small scene





2. BARCODE READING 2D (CAMERA BASED) EXPLANATIONS (FOCAL LENGTH AND LENS)



- Dependency
 - Focal length \leftrightarrow Field of view



Looking at a computer keyboard with different lenses











2. BARCODE READING 2D (CAMERA BASED) EXPLANATIONS (FOCUS)



• A sharp image is well focused



- The focus is used to sharpen the image. There are various types of focuses.
- ► Example:



2. BARCODE READING 2D (CAMERA BASED) EXPLANATIONS (TYPES OF FOCUSES)



- Fix Focus
 - The focus is set to a certain reading distance and can not be changed.
- Mechanical Focus
 - The focus can be changed mechanically during commissioning.
- Dynamic Focus
 - The focus can be changed during the reading gate by command or incoming event such as hardware input.
- Teach Auto Focus
 - The focus can be set automatically by the device, but only when commissioning the device NOT during reading mode.
- Auto Focus
 - The focus is automatically done by the device even during reading gate / trigger



2. BARCODE READING 2D (CAMERA BASED) EXPLANATIONS (APERTURE)



- The aperture is the hole inside the optics through which the light enters the camera
- A small hole means a high aperture number (e.g. f/12)





- Small hole \rightarrow High aperture number
- Big hole \rightarrow Small aperture number
- Example



Aperture: f/4.5

- ightarrow small amount of light
- \rightarrow big amount of light
- \rightarrow darker image
- \rightarrow brighter image



Aperture: f/28

2. BARCODE READING 2D (CAMERA BASED) EXPLANATIONS (DOF)



- The "Depth of Field" (DOF) is the range in which a scene appears acceptably sharp.
- Within the DOF, a sensor can read a code or detect an object, without changing focal position or lens.
- The depth of field depends on
 - Focal length / Focal position
 - Working / Reading distance
 - Lens
 - Aperture
 - Camera sensor resolution
- Main effects
 - Large aperture
 - Long focal length \rightarrow small DOF
 - Short working distance \rightarrow small DOF
- → small DOF
- Small aperture
- Short focal length
- Long working distance
- \rightarrow large DOF
- \rightarrow large DOF
- \rightarrow large DOF

2. BARCODE READING 2D (CAMERA BASED) VERSIONS (LINE & MATRIX CAMERA)



ID (line camera)

- Collects gray or color profiles
- Profiles can be assembled into an image => 2D
- Scanning requires object movement
- 2D (matrix camera)
 - Acquires an area image
 - Snapshot "click", no movement needed

Strtength 1D (line camera)

- Can read smaller code heights with high conveyer speed
- Can read from botton through conveyour gap
- Bigger FOV
- Image output for videocoding and OCR (high res)



Strtength 2D (matrix camera)

/Reading in motion and as well stationary
/Easy to install – live image in station
/More DOF without changing the focus
/Lower hardware price & installation costs
/Capture sevaral images, redundancy

2. BARCODE READING 2D (CAMERA BASED) BARCODE 2D (WHY 2D BARCODE)



Most advantages of 2D Barcdoe

- Very high information density
- Requires very small space
- Redundance
- Marking methods (DPM..)

SICK AG, Nimburger Strasse 11, 79276 Reute	OCR/OCV
	1D Code
	2D Stacked Code
	2D Matrix Code

Code Structure		Cost of Reader	Space Require- ments	Information Density	Reading Reliability	Human Readability	Industry
Optical Char- acters (OCR)		High	Very high	Low	Low	Yes	Pharmaceutical, food, automotive, aviation, and aerospace industries
1D		Low	High	Average	Average	With additional optical characters	Consumer goods industry, parcel and postal services
20	Stacked Codes	Average	Average	High	Average	No	Pharmaceutical and consumer goods industries, parcel and postal services
20	Matrix Codes	Average	Low	Very high	High	No	Automotive, electronic, pharmaceutical, aviation, aerospace, and food industries

2. BARCODE READING 2D (CAMERA BASED) BARCODE 2D (STRUCTURE OF 2D BARCODE)



Characteristics

- Cell size
- Symbol size
- Cell form
- ► Finder pattern (L pattern) > as thick as one cell
- Alignment
- Quiet zone

- > variable, typical values 0,1-1mm
- > depending on the content of the code typical values 12x12 - 32x32
- > squared according to ISO/IEC16022
- > twice the size of one cell
- > at least as thick as one cell, but thicker than 5 times the cell size recommended



Symbol size

Data Matrix ECC200

The most common 2D Matrix code !



2. BARCODE READING 2D (CAMERA BASED) BARCODE 2D (MARKING METHODS)



- Examples of marking methods
 - ► InjkJet

► Laser marking

Good

Dot peening (DPM)

► Electr. chem. etching













2. BARCODE READING 2D (CAMERA BASED) COMMON ILLUMINATIONS (WHITE, BLUE, RED)





What lighting color for which task?

WHITE...

- Is the all-purpose version due to widest spectrum
- Is most suitable for codes printed on cardboard boxes
- Suits best for presentation camera applications as most people feel white light is least harmful

BLUE...

- Is the perfect choice if maximum optical DOF is required (f = >11...16)
- Offers best performance if the pixel resolution is challenging (1D <1.5 ppm & 2D < 2.0ppm)
- Is not well-suitable for colored codes printed on cardboard boxes as the brown background turns black

RED...

- Is used if label with white, yellow and red background need to be read
- Can be used if black barcodes are printed on cardboard boxes









Example for a reading diagramm



2. BARCODE READING 2D (CAMERA BASED) TARGET APPLICATIONS FOR 2D (MATRIX CAMERA)



Automotive

- Power train (DPM)
- ► Tire manufacturer
- ► Final assembly

Electronic & Solar

- ► PCB production
- Waver production
- ▶ ...

Consumer goods

- Production
- Packaging
- ▶ ...







2. BARCODE READING 2D (CAMERA BASED) TARGET APPLICATIONS FOR 2D (LINE CAMERA, SYSTEM)

• CEP (courier express parcle), Tire Industrie...

- Omnidirectional reading of 1D and 2D codes
- Image output options for diagnostics and analysis
- Can read smaller code heights with high conveyer speed
- Can read from botton through conveyour gap









3. LASER VS. CAMERA LASERBASED BARCODEREADER VS. CAMERABASED BARCODEREADER ensor Intelligence.

Laser	Task	Camera
+	1D Code	++
-	2D Code	+
- (+)	Omnidirectional reading	+ -
+	Speed	+
+	Start-/Stop and standstill	-
+	Required Space	-
+	DOF (Depth of Field)	-
+	FOV	-
-	Images	+
+	Costs	-

4. RFID WORKING PRINCIPLE

Meaning

Because of the procedures used for the transfer of power and data, contactless ID systems are called RFID systems (Radio Frequency Identification)



Principle of an RFID System

- The Tag applied to an object carries data along the logistic process.
- : The Interrogator supplies energy and data to the Tag by using the antenna.
- : The Interrogator may read from or write onto the Tag.
- : The Interrogator is controlled by a PLC or a higher level System like ERP or WMS via a LAN.

*ERP: Enterprise Resource Planning *WMS: Warehouse management System



4. RFID MOST FAMOUS RFID FREQUENCIES



	LF - 125 kHz	HF - 13,56 MHz	UHF - 860960 MHz	MW - 2,45 GHz
Write-/ Read Range	up to 0,7 m	up to 0,5 m	up to 5 m	up to 10 m
Object speed	max. 2 m/s	max. 6 m/s	max. 10 m/s	max. 25 m/s
Material penetration	all except Metal	all except Metal	low	Reflexions
ISO-Standards	11784	15693/18000-3, 14443	18000-6	10374
Main applications	Access control, Tool-ID, Animal-ID	Tote-ID, Library, Laundry, e-passport	Parcel-ID, Pallet-ID, Luggage-ID	Traffic (Maut) Container
Market share	high	medium, growing	medium, growing	low



4. RFID HF RFID BASICS



Technical view - magnetic Coupling

Low and high frequency systems are based on the magnetic coupling principle to transfer energy and data. The interrogator generates a magnetic field. The transponder is able to store and transmit data. The achievable read write performance is closed to the theoretic values.



4. RFID UHF RFID BASICS



Technical View – electro magnetically principle

 Ultra high frequency RFID systems uses an electrical field to transmit energy and data The Interrogator generates an electromagnetic field
 The transponder is able to send and store data
 Transponder gets his energy out of the field
 The Transponder sends data using backscatter technique





 The UHF field is complex and electro dynamic The field distribution is comparable to light The characteristic is similar to a cell
 The usage of circular polarized antennas is preferred
 The movement of a transponder is preferred



4. RFID UHF/HF RFID BASICS

The general rule

- ► HF > Metal absorb, water causes no problems
- ► UHF > Metal reflectet, water acts dampen, regional differences in frequency !!

<u>!! Message !!</u>	<u>!! Message !!</u>
HF (13,56MHZ)	UHF (860-960MHZ)
 magnetic coupling near field technology suited for static use 	 capacitive coupling far field technology dynamic applications preferred

Additional Information

- UHF can also be used in near field applications by using special transponders
- UHF is the preferred technology for open systems
- ► HF is suitable for intralogistic applications (short-range)

Länder	UHF Frequenz Bänder
Europe	865 – 868 MHz
USA	902 – 928 MHz
Korea	908 – 914 MHz
Singapore	923 – 925 MHz
Australia	923 – 928 MHz
Japan	950 – 960 MHz
China	ungefähr 900 MHz



4. RFID READINGFIELD DIAGRAMM



Example of a readingfield diagramm for HF

► With different transponders



4. RFID TARGET APPLICATIONS FOR HF (STAND ALONE DEVICES)



Textil industry



Warehouse (Forklift)



Intralogistic



Automotive



4. RFID TARGET APPLICATIONS FOR UHF (STAND ALONE DEVICES)



Intralogistic



Warehouse (Forklift)



Storage & Conveyour



Automotive



5. LASER VS. CAMERA RFID TECHNOLOGY VS. BARCODETECHNOLOGY

RFID	Task	Barcode
+	Read without visual contact	-
+	Environmental resistance	-
+	Bulk Reading	-
+	Rewriteable transponder/label	-
+	Large data memory transponder/label	-
+	Lifetime	-
+	Maintenance	-
-	Technology not visible	+
-	Costs transponder/label	+
+	Range	-

6. OVERVIEW PORTFOLIO - IDENTIFICATION LASER / CAMERA / RFID (SERIAL PRODUCTS)





6. OVERVIEW PORTFOLIO - IDENTIFICATION LASER / CAMERA / RFID (SYSTEME)



Twin Head (Omnilesung - 1 Seite)



OPS (Omnilesung, bis zu 6 Seite)



DWS





ICR8xx (Line camera)



DWS (Dimensioning/Weighting/Scaning)



RFGS PRO (Gate – Solution)



RFMS PRO (Tunnel – Solution)



6. CONNECTION TECHNOLOGY CONCEPT 4D PRO



- All 4D PRO devices are compatible and interchangable via our standardized 4D PRO plattform
 - Same connection technology Same user interface (SOPAS) Same accessory concept CDF600-2100 CDF600-2103 RFID ++++10 **RFID** Kamera Laserscanner 1D 1D 2D

THANKS FOR YOUR ATTENTION!

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Productmanagement "Identification & Measuring"



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